

Turbulence control—From model-based to machine learned

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Abstract

Turbulence control is a critical enabler of aerodynamic drag reduction, lift increase, mixing enhancement, and noise reduction. Current and future applications have epic proportion: cars, trucks, trains, airplanes, wind turbines, medical devices, combustion, chemical reactors, just to name a few. A key feature, opportunity and technical challenge is the inherent nonlinearity of the actuation response [1]. For instance, excitation at a given frequency will affect also other frequencies. This frequency cross-talk is not accessible in any linear control framework.

In these lectures, we discuss a spectrum of turbulence control strategies. Starting point is human-learned nonlinear model-based control explaining the dynamics with one or few dominant frequencies [2] in analytical detail. This path follows the traditional control philosophy

understanding \mapsto modeling \mapsto control \mapsto tuning in experiment,

may work beautifully for simple dynamics but is less suited for the jungle of nonlinear surprises.

Recently, artificial intelligence / machine learning has opened a game-changing elegant new avenue [3]: the automated model-free discovery and exploitation of unknown nonlinear interactions directly in the plant. This avenue leads to the new faster, easier (student-proof) paradigm,

experiment \mapsto control \mapsto modeling \mapsto understanding,

with numerous success stories in experiments. In between the extremes of model-based and model-free strategy, cluster-based networks emerge as enabler for automated modeling *and* control. The following topics will be discussed:

(1) Model-based control (part 1).

- a) Reduced-order modeling—POD Galerkin method.
- b) Modeling and control of a single frequency dynamics.
- c) Modeling and control of two/multiple frequency dynamics.

(2) Model-free machine learning control (part 2).

- a) Control as regression problem—Genetic programming.
- b) Machine learning control.
- c) Control landscapes—Cartographing the learning.

(3) Cluster-based control (part 3).

- a) Coarse-graining snapshots—Clustering.
- b) Cluster-based modeling.
- c) Cluster-based control.

(4) Principles of control (part 4).

- a) Physical actuation mechanisms.
- b) Pairing methods with problems.
- c) Good practices for the experiment.

Reading material: Our review article [1] provides the roadmap for the spectrum of turbulence control methods taught in this class. Model-based and model-free flow control are described in detail in our Springer textbooks [2, 3].

POD-based reduced-order modeling (part 1) is covered in the classics by Holmes et al. [4]. An inspired hands-on introduction of control methods is provided by Aström & Murray [5]. Burkov [6] is an excellent primer of machine learning as basis for part 2–4. Evolutionary algorithms (part 2) are beautifully described in the short book of Wahde [7].

Perhaps the best start is our review article [1]. The machine learning primer [6] will be useful for any modern research beyond these lectures. From there on, the recommended reading may be based on time and interest.

References

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